



CSCI 1106

Lecture 9

Using State Transition Diagrams



Announcements

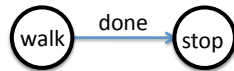
- Today's Topics
 - States, transitions, and program blocks
 - Mapping state transition diagrams to programs
 - Discussion

Recall

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States and Transitions

- State
 - Unique set of conditions
 - Describes a step of a task
 - Represented by a circle and a label
- Transition
 - Change of one or more conditions
 - Describes a change from one state to another
 - Represented by a labeled arc



Program Blocks

- Sense blocks



- Decide blocks



wait



loop



Switch (if)

- Action blocks



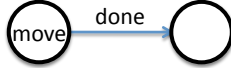

Translating State Transition Diagrams

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- Problem:
 - We design our solution by creating a state transition diagram (STD)
 - We need to translate the STD into a program
- Idea: Divide and Conquer
 - Identify standard patterns in STD
 - Implement each pattern using one or more program blocks
- How do we identify the patterns?

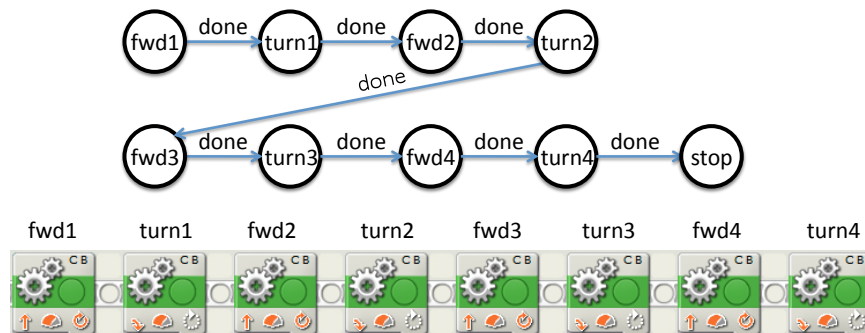


Standard Patterns

- Idea: We consider all the blocks and ask, what patterns do they implement?
- We start with simplest: Action Blocks
 - Synchronous Move: 
 - Asynchronous Move: 
 - Any other action will yield the same patterns



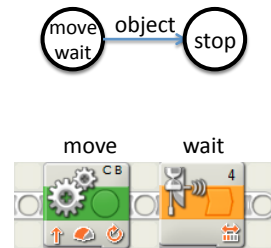
Example: Move in a Square



- The “stop” state is implicit in the program
- Transitions are triggered by internal events (action completions)
- The program can be shortened by using a loop

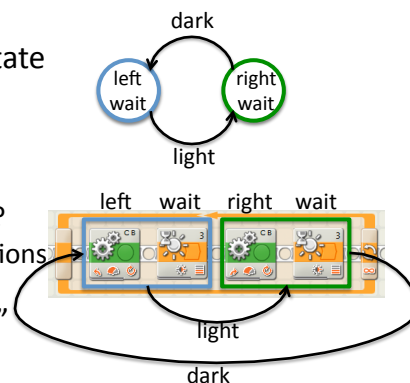
The Wait Block (Sense-Decide)

- The Wait block is used to represent a state and a transition due to an external event
- Use it after an asynchronous action
- Example: Move forward until an object is encountered
- Note: Only one transition can occur from an “action + wait” state.
 - Why?
 - Why would this be inadequate?
 - How do we get around this?



The Loop Block

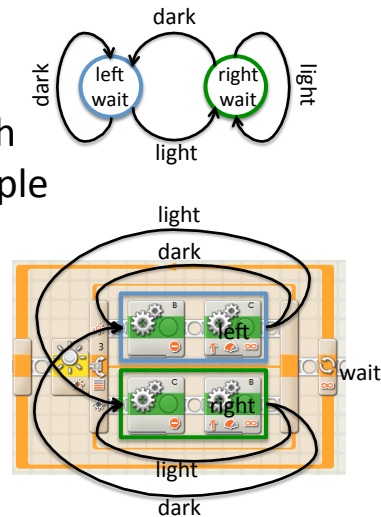
- The Loop Block is used to implement loop structures in a STD
- The loop allows us to repeat a state
- Easy if you have only one cycle
 - Even if more than two states
- Questions:
 - What if you have multiple cycles?
 - What if you have multiple transitions from states?
- Answer: Bring out the “big guns”
 - The Switch (if) Block



The Switch (If) Block

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- Recall the definition of a *state* ...
- Idea: Use a loop and switch blocks to implement multiple states and cycles
- Example: Follow the line
- Questions:
 - Where is the “wait”?



The True Meaning of State

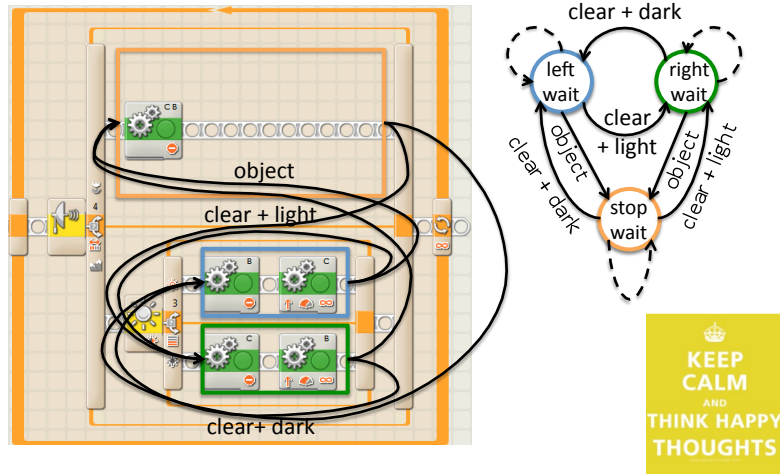
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- Observations:
 - A state is defined by a set of conditions
 - A switch (if) block can be used to test for conditions
- Idea: Use switch blocks to test what state the system is in each time through the loop

Example: Follow but Stop

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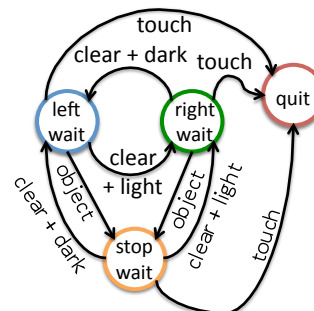
- Follow the line but pause for objects in the way



More Complexity

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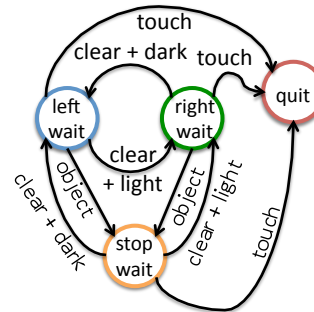
- Suppose we wanted add another constraint:
 - Stop and quit if rear touch sensor is activated
- Our STD gets another state
- The program becomes even more complex
- How do we change the program?



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Options for Implementing the Changes

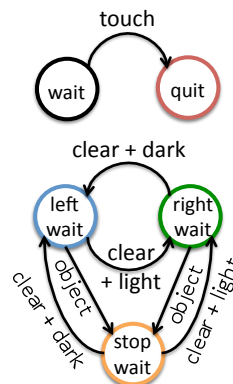
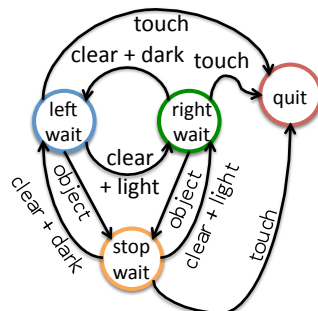
- Add another Switch Statement
 - Standard, but adds complexity
- Change loop condition
 - STD is still complex
- Use multiple threads and simplify the STD
 - Two simple STDs are easier to implement than one complex STD

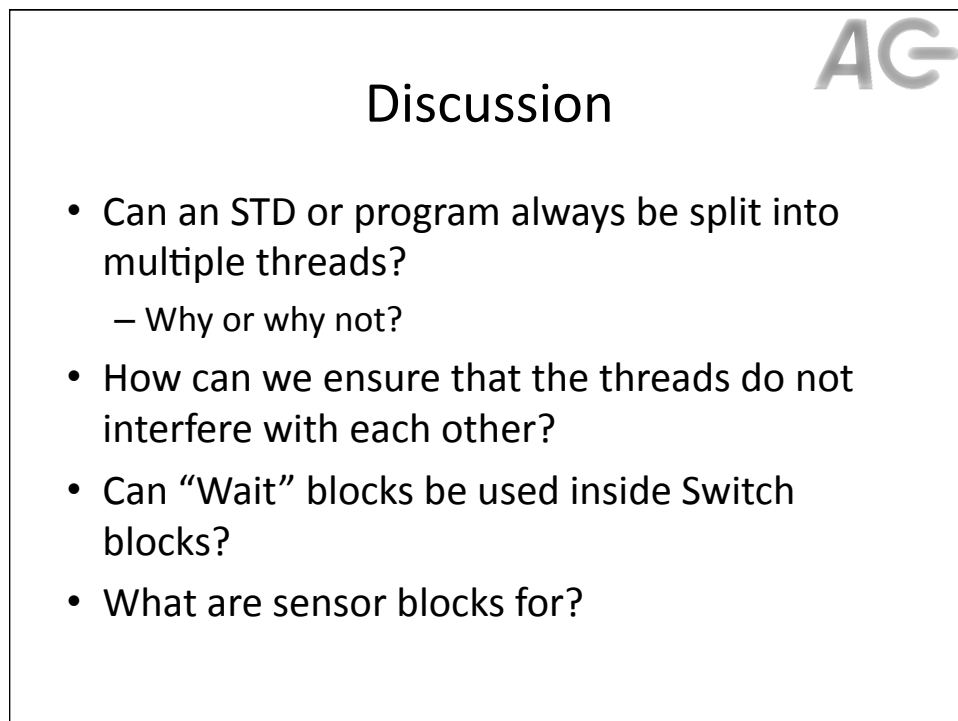
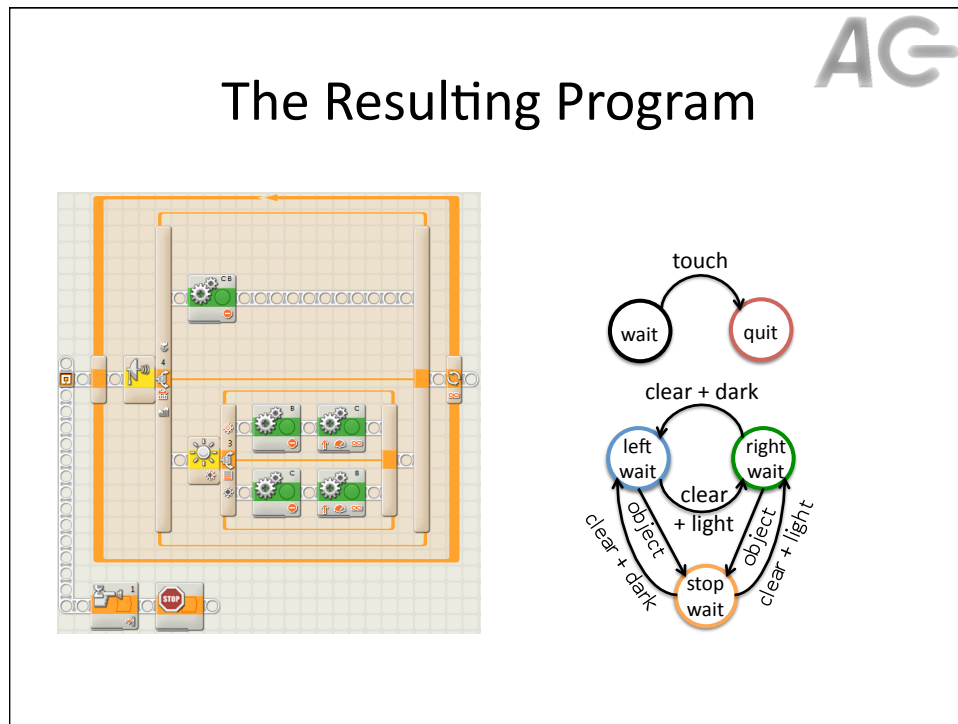


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Simplifying the STD

- Break one STD into two
- Use one thread per STD





Why Do We Need Sensor Blocks?

- Viewing the measurements that a sensor is reporting when debugging a program
- Keeping track of previous measurements to compare against future measurements
 - E.g., Finding a minimum/maximum measurement
- Creating multiconditional Wait blocks

Multiconditional Wait Blocks

- A Wait block polls a sensor until a threshold is reached
- Idea: Combine measurements from multiple sensors

